

The PACF & Estimation for ARMA

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Which **basic** models might these simulated data come from? AR(1), MA(1), or white noise

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ACF

One is AR(1), $\alpha_1 = 0.6$ The other is ARMA(1, 1), $\beta_1 = 0.5$, $\alpha_1 = 0.5$



Partial autocorrelation function

Basic idea: what is the correlation between x_t and x_{t+h} , after taking into account x_{t+1} , x_{t+2} , ..., x_{t+h-1} ?

Technically:

Regress x_t on x_{t+1} , x_{t+2} , ..., x_{t+h-1} to find the fitted value \hat{x}_t .

Regress x_{t+h} on x_{t+1} , x_{t+2} , ..., x_{t+h-1} to find the fitted value \hat{x}_{t+h} .

Find cor(x_t - $\hat{x}_{t, x_{t+h}} - \hat{x}_{t+h}$), call this PACF(h) = $\mathbf{\Phi}_{hh}$

PACF

 $\left|\right\rangle$







| | MA(q) | AR(p) | ARMA(p,q) |
|------|------------------|------------------|-----------|
| ACF | zero lags > q | tails off | tails off |
| PACF | tails off | zero lags > P | tails off |

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Corvallis temperature

Series corv\$residual



Corvallis temperature

pacf(corv\$residual, na.action = na.pass)
 Series corv\$residual



ARMA(p,q)

Assume we know the order of our process, i.e. we know p and q.

How do we estimate the βs , αs , and σ^2 ?

Your turn

Name three common approaches to finding an estimate:

Hints:

M of M

L S

M

The default in R Has nice properties



We have the theoretical ACF in terms of α , β and σ .

Set the theoretical ACF equal to our sample ACF and solve for the parameters.

So, we don't get too confused, let $\rho(h)$ denote the the theoretical ACF, and r(h) the sample ACF.

Corvallis temperature

- Assume the residuals can be modelled by an AR(1).
- $\rho(1) = \Phi$ $\hat{\phi} = \alpha$, notation slip r(1) = $\hat{\phi} = 0.6607$

For AR(p) processes we write down a recursion,

$$\rho(h) = \phi_1 \rho(h-1) + \ldots + \phi_p \rho(h-p), \quad h = 1, \ldots, p$$

 $\sigma^2 = \gamma(0) \left(1 - \phi_1 \rho(1) - \ldots - \phi_p \rho(p)\right)$

The Yule-Walker equations

Derive Yule-Walker eqns

Yule-Walker Estimates

$$r(1) = \hat{\phi_1} + \hat{\phi_2}r(1) + \dots + \hat{\phi_p}r(p)$$

$$r(2) = \hat{\phi_1}r(1) + \hat{\phi_2} + \dots + \hat{\phi_p}r(p-2)$$

$$\vdots$$

$$r(p) = \hat{\phi_1}r(p-1) + \hat{\phi_2}r(p-2) + \dots + \hat{\phi_p}$$

A set of p equations in p unknowns, solve for $\hat{\phi_1}$ to $\hat{\phi_p}$.

MA(q) and ARMA(p,q)

The method of moments approach gets complicated. End up with non-linear equations to be solved numerically.

The method of moments estimators have bad properties for MA and ARMA processes anyway, so we'll leave it here.

Your turn

Remember linear regression?

$$y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$$

We can find estimates for $\beta_0\,,\beta_1$ by minimizing

$$\sum_{i=1}^{n} \left(y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i \right)^2$$



Consider the AR(1) process

 $X_t = \alpha_1 X_{t-1} + W_t$

Define the residual, $e_t = x_t - \hat{\alpha_1} x_{t-1}$

We could consider finding the $\hat{\alpha}_1$ that minimises the sum of squared residuals,

 $\sum_{t=2}^{n} (x_t - \hat{\alpha_1} x_{t-1})^2 = \sum_{t=2}^{n} e_t^2$ Since we don't see x₀

called conditional least squares

L____S___for MA

In general we can always define these residuals, but for MA and ARMA processes they are recursive. For example, MA(1)

$$e_1 = x_1 + \beta_1 e_0$$
 assume $e_0 = 0$
 $e_2 = x_2 + \beta_1 e_1$

$$\vdots$$
$$e_n = x_n + \beta_1 e_{n-1}$$

L_____S____in ARMA

For a general ARMA(p,q):

$$e_t = x_t - \alpha_1 x_{t-1} - \dots - \alpha_p x_{t-p} + \beta_1 e_{t-1} + \dots + \beta_q e_{t-q}$$

And we have to set $e_p = ... = e_{p+1-q} = 0$, and sum starting at t = p, to avoid the x_t we haven't observed

The minimization is done numerically

Assume a distribution for the white noise (usually Gaussian), then write the joint density function of our data as a function of the parameters, the likelihood,

 $L(\beta, \, \theta, \, \sigma^2) = f(x_1, \, x_2, \, \dots \, x_n; \, \beta, \, \theta, \, \sigma^2)$

Find the parameters that maximise the likelihood.

For the non-statisticans: The joint density, f, tells us the probability of our data given certain parameter values. The likelihood, L, tells us how *likely* certain parameters are given our data (f and L are the same function, we just switch what we consider to be the variable). We estimate the parameters by choosing the most likely parameters given the data we saw.

Assuming our white noise is Gaussian then the ARMA(p, q), x_t, process is also Gaussian and the likelihood is

$$x_t \sim Normal_n(\mathbf{0}, \Sigma)$$

where
$$\Sigma_{ij} = Cov(x_i, x_j) = \gamma(|i - j|)$$

It's complicated, but there are general algorithms for maximizing it.

Maximum Likelihood

The way the function arima in R does it by default.

Nice asymptotic properties, deals with missing data easily.

Always lower variance than method of moments.



I'm out of town. Chris will lead lecture. Bring laptops!